

Features of assessing the efficiency of vehicle operation in port conditions using monitoring systems of various configurations

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MARITIME, OFFSHORE ENERGY, and PORT
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Introduction

- Complexity of vehicle operation in port environments
- Challenges: downtime, safety, and fuel efficiency
- Growing need for advanced monitoring systems
- Goal: Present systematized methods for assessing and improving operational efficiency





Operational Challenges in Port Conditions

- High vehicle turnover and congestion
- Unpredictable delays and idle time
- Harsh infrastructure and weather conditions
- Spare parts and maintenance inefficiencies



Role of Monitoring Systems

- Real-time data acquisition from vehicles, operators, cargo, and environment
- Benefits:
 - Proactive maintenance
 - Improved safety
 - Performance optimization

Five Hardware Groups of Functional Components of Monitoring

1. Operator condition monitoring
2. Vehicle technical state monitoring
3. Cargo status tracking
4. Infrastructure condition sensing
5. Data processing and consumption tools

Morphological Matrix Approach

- Introduced by Prof. Vasyl Mateichyk
- 20 morphological traits across hardware groups
- Over 450 billion possible configurations
- Allows tailored system design

$$\left[\begin{array}{l} (x_{14}; x_{23}; x_{32}) + (x_{41}; x_{51}; x_{61}; x_{72}; x_{82}) + \\ + (x_{91}; x_{101}; x_{111}; x_{121}) + (x_{132}; x_{143}; x_{154}; x_{163}) \\ + (x_{172}; x_{182}; x_{193}; x_{202}) \end{array} \right]$$

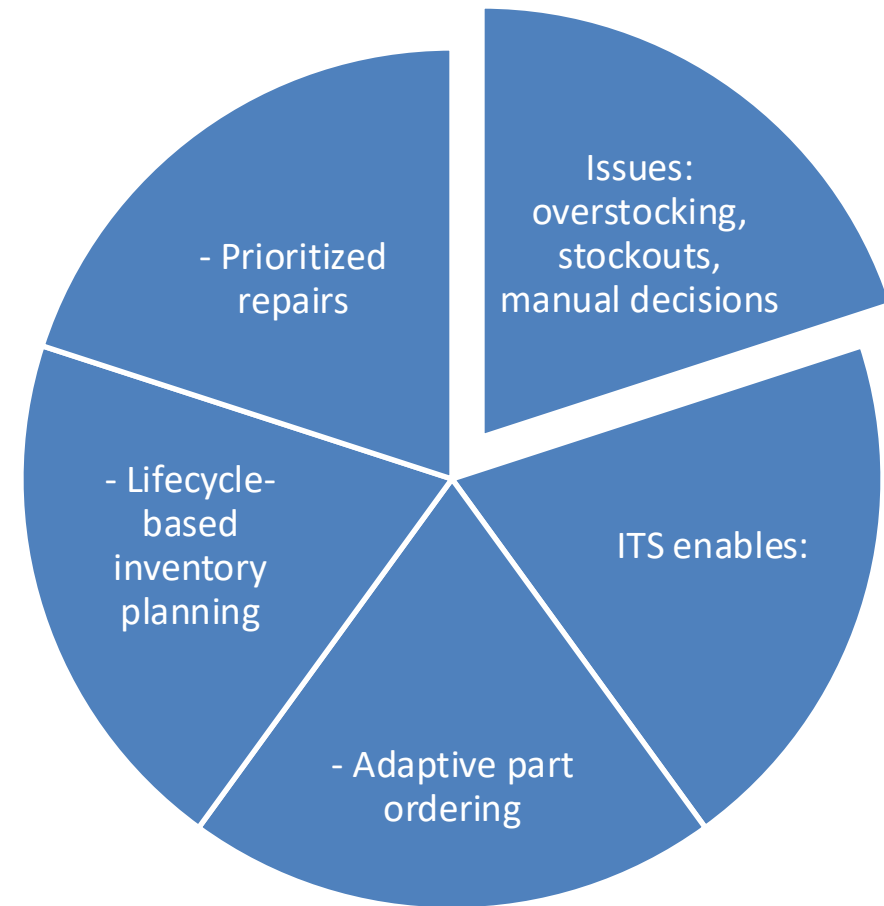
Functional Element	Morphological Trait	Options (Examples)
Operator Monitoring	Type of Information	Personal data, biometric data, status codes
	Method of Collection	Wearable sensors, cab-mounted cameras, workplace sensors
	Data Transmission	Local storage, mobile networks, hybrid
Vehicle Monitoring	Information Type	Diagnostic codes, fuel consumption, operational logs
	Sensor Type	Standard onboard sensors, added sensors, infrastructure-based detection
	Processing Location	Onboard unit, cloud server, combined
	Transmission Method	Local memory, mobile/internet, combined
Cargo Monitoring	Data Collected	Temperature, movement, shock, absence of data
	Tracking Method	RFID, IoT sensors, manual logs
	Transmission Method	Stored onboard, wireless sync, satellite
Infrastructure Data	Parameters Monitored	Road condition, traffic, weather
	Sensor Location	Vehicle-mounted, roadside, hybrid
	Data Sharing	Cable, wireless, gadgets
Data Analysis & Use	Storage Strategy	Onboard, cloud, hybrid
	Retention Period	Short-term, long-term, permanent
	Usage Level	Informational, control & diagnostics, predictive maintenance, performance evaluation

An abstract digital cityscape rendered in shades of blue. It features several 3D cubes of varying sizes, some of which are hollow and glow from within. The surfaces of the cubes and the background are filled with a dense, vertical stream of small, glowing characters, reminiscent of the 'Matrix' effect. Several bright, colored beams (red, green, and blue) originate from different points and intersect, creating a sense of dynamic data flow and connectivity.

Example Configuration (Simplified)

- Operator: biometric sensors → cellular data transmission
- Vehicle: onboard diagnostics → cloud processing
- Cargo: RFID tracking → local storage
- Infrastructure: weather sensors → satellite uplink
- Output: dashboards for diagnostics and planning

Downtime & Spare Parts Optimization



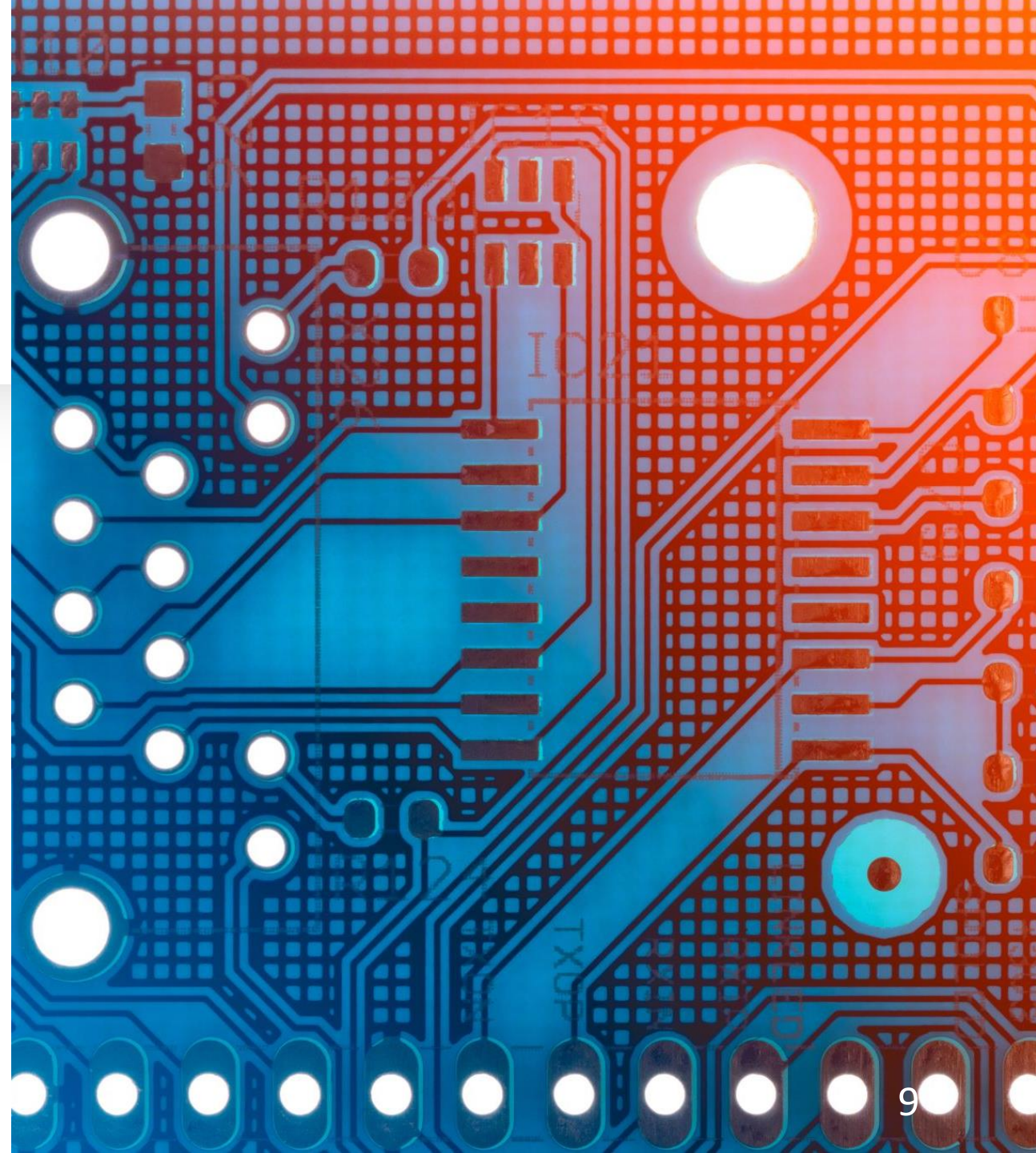
Integrated System: Vehicle + Infrastructure

Components:

- Intelligent sensors
- Remote diagnostics
- Spare parts coordination

Effects:

- Reduced fuel use and emissions
- Minimized idle time



Analytical Model



Objective: Maximize operability $Q(GPt)$, minimize consumption GPt



Factors:



- Fuel use



- Load



- Infrastructure quality



- Driver behavior



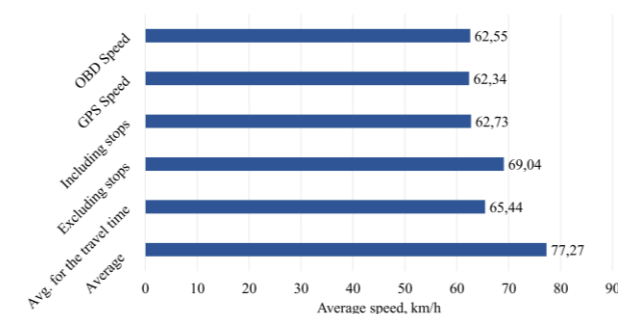
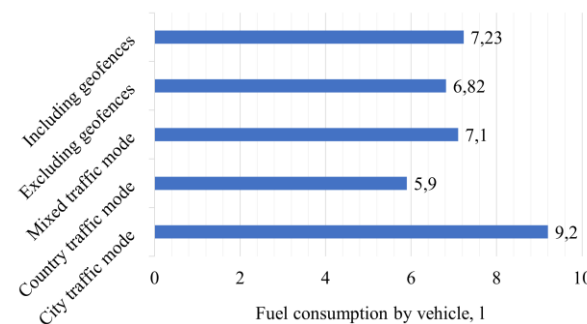
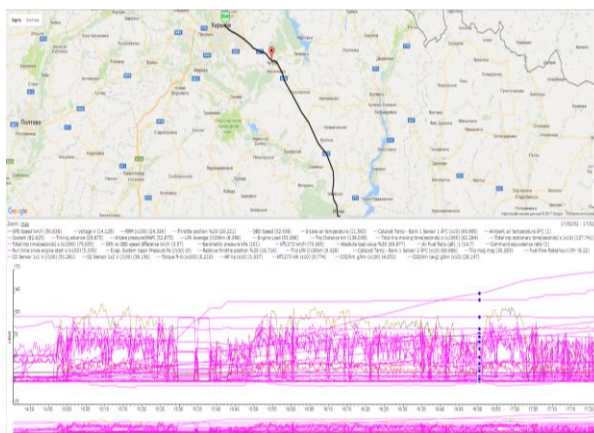
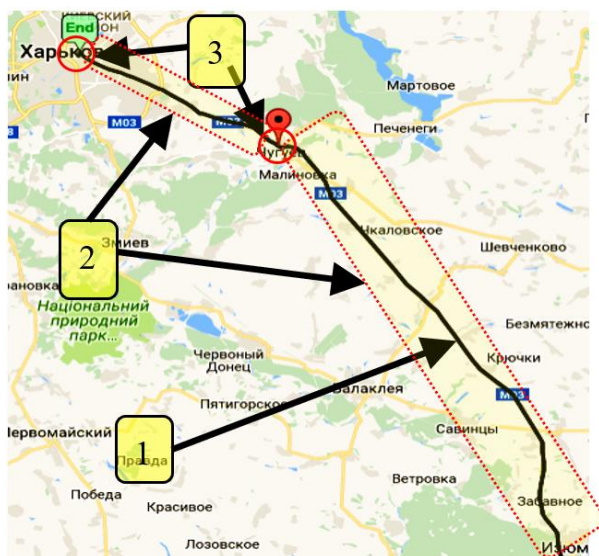
Combines logistics and predictive analytics

$$\left\{ \begin{array}{l} F_{Gtp}(\bar{H}_t, t, \Delta t, \bar{X}_i(t), \bar{X}_i(t - \Delta t), \dots, \bar{X}_i(t - n \Delta t), DK_{ti}) = S_{GP}; \\ S_{GP} = \Omega_l^{m_i}(e_Q, r)^j; \\ S_{GP} = F_{Gtp}(S_{T3S}; S_{T3L}; S_{T3M}); \\ S_{GP} = F_{Gtp}((M_{i1}, M_{i2}, M_{i3}); (T_{ST3}, P_{DU})); \\ M_{i1} = F_{i1i}(\bar{X}_{Gmti}(t)); \\ M_{i2} = F_{i2i}(\bar{X}_{G2ti}(t)); \\ M_{i3} = F_{i3i}((\bar{X}_{Mt13i}(t)); (\bar{X}_{Mt23i}(t)); (\bar{X}_{Mt33i}(t)); (\bar{X}_{Mt43i}(t))); \\ T_{ST3} = F_{ST3i}((\bar{X}_{Gmti}(t)); DK_{ti}); \\ P_{DU} = F_{Dui}(\bar{X}_{Duit}(t)); \\ Pr(t) = F(t, M_{43}) \rightarrow \min; \\ S_{ZA}(t) = F(t, N_z, M_{43}) \rightarrow \min. \end{array} \right.$$

$$\left\{ \begin{array}{l} Q(GPt) = F((M_{i1}, M_{i2}, M_{i3}(M_{12}, M_{23}, M_{33}, M_{i43})); (T_{ST3}, P_{DU})) \rightarrow \max; \\ G_{Pt} \rightarrow \min; \\ Pr(t) = F(t, M_{43}) \rightarrow \min; \\ S_{ZA}(t) = F(t, N_z, M_{43}) \rightarrow \min. \end{array} \right.$$

Real-world Application

- Geofencing for urban/rural differentiation
- Tracking speed and fuel consumption
- Reports enable: fault alerts, diagnostics, maintenance triggers



Practical Recommendations

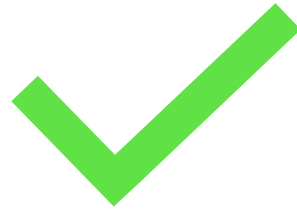
- Apply hybrid ITS in port logistics
- Use morphological matrix for system design
- Focus on:
 - Reducing idle time
 - Enhancing decision support
 - Predictive diagnostics



Conclusions



Monitoring systems
offer scalable solutions



Morphological method =
tailored efficiency



ITS + logistics models =
robust port operations

Thank you for your attention